

# Errors from Controller

The specific errors of the robot controller are listed in the following table:

Error	Description
-3001	*E-stop due to lost communications with PLC*
-3007	*Invalid command: More than one command bit enabled*
-3008	*Only one axis bit can be set while jogging*
-3009	*Cannot mix joint-coordinate location and pallet*
-3010	*Cannot move relative to a pallet*
-3011	*Invalid location number* Location n
-3012	*Invalid pallet number* Pallet n
-3013	*Invalid speed parameter* Speed n
-3014	*Invalid acceleration/deceleration parameter* Value n
-3015	*Undefined location* Location n
-3016	*Undefined pallet* Pallet n
-3019	*ePLC Connect start-up error* Code n Here are the possible causes: invalid eV+ software version, invalid eV+ software license, or invalid ePLC connection application license.
-3020	*Invalid approach parameter for this robot*
-3021	*Pallet locations are linear*
-3022	*Invalid pallet index* Position n
-3024	*Adept ACE Control mode enabled*